

## Math 601 Midterm 2 Solution

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Question	Points	Score
1	15	
2	10	
3	10	
4	15	
5	10	
6	10	
7	10	
8	10	
9	10	
Total:	100	

Question	Bonus Points	Score
Bonus Question 1	5	
Total:	5	



**Question 2. (10 pts)**

Determine whether the matrix  $A = \begin{bmatrix} 2 & 3 & 2 \\ 0 & 2 & 0 \\ 0 & 2 & 2 \end{bmatrix}$  is diagonalizable.

**Solution:** Use cofactor expansion along the first column

$$\det(A - \lambda I) = \begin{vmatrix} 2 - \lambda & 3 & 2 \\ 0 & 2 - \lambda & 0 \\ 0 & 2 & 2 - \lambda \end{vmatrix} = (2 - \lambda)^3$$

So  $\lambda = 2$  is an eigenvalue with multiplicity 3.

Now solve for the eigenvectors belonging to  $\lambda = 2$ , i.e. the kernel of the matrix

$$\begin{vmatrix} 0 & 3 & 2 \\ 0 & 0 & 0 \\ 0 & 2 & 0 \end{vmatrix}$$

So there is only one linearly independent eigenvector  $v = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ .

We need 3 linearly independent eigenvectors for  $A$  to be diagonalizable. By the above calculation, we see that  $A$  is not diagonalizable.

**Question 3. (10 pts)**

The eigenvalues and corresponding eigenvectors of the matrix  $A = \begin{bmatrix} 1 & -3 & 3 \\ 3 & -5 & 3 \\ 6 & -6 & 4 \end{bmatrix}$  are  $\lambda_1 = -2$  with  $v_1 = (1, 1, 0)^T$ ,  $\lambda_2 = -2$  with  $v_2 = (1, 0, -1)^T$  and  $\lambda_3 = 4$  with  $v_3 = (1, 1, 2)^T$ . Find the general solution to the system

$$\frac{d\mathbf{x}}{dt} = A\mathbf{x}.$$

**Solution:** The general solution is

$$\mathbf{x}(t) = c_1 e^{-2t} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + c_2 e^{-2t} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + c_3 e^{4t} \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$$

In other words,

$$\begin{bmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \end{bmatrix} = \begin{bmatrix} c_1 e^{-2t} + c_2 e^{-2t} + c_3 e^{4t} \\ c_1 e^{-2t} + c_3 e^{4t} \\ -c_2 e^{-2t} + 2c_3 e^{4t} \end{bmatrix}$$

**Question 4. (15 pts)**

Recall that  $S = \{1, t, t^2\}$  is a basis of  $\mathbb{P}_2(t)$ . Let  $F : \mathbb{P}_2(t) \rightarrow \mathbb{P}_2(t)$  be the linear transformation defined by

$$F(1) = 1 + t^2, F(t) = 2 + t + t^2 \text{ and } F(t^2) = -1 + t - 2t^2$$

- (a) Write down the matrix representation of  $F$  relative to the basis  $S = \{1, t, t^2\}$ .

**Solution:**

$$[F]_S = \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & 1 \\ 1 & 1 & -2 \end{bmatrix}$$

- (b) Find the kernel of  $F$ .

**Solution:** First reduce the matrix  $[F]_S$  in part (a) to its echelon form, which is

$$\begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

So  $\text{Ker}F = \text{span}\left\{ \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix} \right\}$ . In other words,  $\text{Ker}F$  is spanned of one polynomial  $3 - t + t^2$ .

(c) Find the dimension of the image of  $F$ .

**Solution:**

$$\dim(\text{Im}F) + \dim(\text{Ker}F) = 3$$

From part (b), we know that  $\dim(\text{Ker}F) = 1$ . So  $\dim(\text{Im}F) = 2$ .

(d) Is  $F$  is an isomorphism? Explain.

**Solution:** Since  $\text{Ker}F$  is not equal to the zero vector space  $\{0\}$ , we see that  $F$  is not an isomorphism.

**Question 5. (10 pts)**

Find all eigenvalues and eigenvectors of the matrix

$$A = \begin{bmatrix} 4 & 2 - i \\ 2 + i & 0 \end{bmatrix}$$

**Solution:**

$$\det(A - \lambda I) = \begin{vmatrix} 4 - \lambda & 2 - i \\ 2 + i & -\lambda \end{vmatrix} = -\lambda(4 - \lambda) - 5 = (\lambda - 5)(\lambda + 1)$$

When  $\lambda = 5$ , the eigenvector is

$$v = \begin{bmatrix} 2 - i \\ 1 \end{bmatrix}$$

When  $\lambda = -1$ , the eigenvector is

$$w = \begin{bmatrix} -1 \\ 2 + i \end{bmatrix}$$

**Question 6. (10 pts)**

Let  $U$  be the subspace of  $\mathbb{R}^4$  spanned by  $v_1 = (1, 7, 1, 7)$ ,  $v_2 = (0, 7, 2, 7)$  and  $v_3 = (1, 8, 1, 6)$ . Find an orthogonal basis of  $U$ .

**Solution:**

$$w_1 = v_1 = (1, 7, 1, 7)$$

$$w_2 = v_2 - \frac{\langle w_1, w_2 \rangle}{\langle w_1, w_1 \rangle} w_1 = (-1, 0, 1, 0)$$

$$w_3 = v_3 - \frac{\langle w_1, w_3 \rangle}{\langle w_1, w_1 \rangle} w_1 - \frac{\langle w_2, w_3 \rangle}{\langle w_2, w_2 \rangle} w_2 = (0, 1, 0, 1)$$

**Question 7. (10 pts)**

Let  $V$  be the vector space spanned by the basis  $S = \{1, \cos t, \sin t\}$ . Determine whether the functions

$$f_1(t) = 1 + 2 \cos t + 3 \sin t$$

$$f_2(t) = 2 + 5 \cos t + 7 \sin t$$

$$f_3(t) = 1 + 3 \cos t + 5 \sin t$$

are linearly independent or not. (**Hint: try to use the corresponding coordinate vectors with respect to the basis  $S$ .**)

**Solution:**

$$[f_1]_S = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$$[f_2]_S = \begin{bmatrix} 2 \\ 5 \\ 3 \end{bmatrix}$$

$$[f_3]_S = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}$$

Consider the matrix

$$\begin{bmatrix} 1 & 2 & 1 \\ 2 & 5 & 3 \\ 3 & 7 & 5 \end{bmatrix}$$

its echelon form is

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

which has rank 3. Therefore  $f_1$ ,  $f_2$  and  $f_3$  are linearly independent.

**Question 8. (10 pts)**

Let  $\mathbb{P}_2(t)$  be the vector space of polynomials with degree  $\leq 2$ . Suppose the linear transformation  $B : \mathbb{P}_2(t) \rightarrow \mathbb{P}_2(t)$  is defined by

$$B(p) = p(0) + p(1)t + p(2)t^2$$

for every polynomial  $p \in \mathbb{P}_2(t)$ . Note that here  $p(0)$  (resp.  $p(1), p(2)$ ) is the value of the polynomial  $p(t)$  at  $t = 0$  (resp.  $t = 1, 2$ ). In particular,  $p(0), p(1)$  and  $p(2)$  are real numbers, and  $p(0) + p(1)t + p(2)t^2$  is a polynomial in  $\mathbb{P}_2(t)$ . Show that  $B$  is an isomorphism. (**Hint: try to use the matrix representation of  $B$  relative to a basis.**)

**Solution:** Note that

$$B(1) = 1 + t + t^2$$

$$B(t) = t + 2t^2$$

$$B(t^2) = t + 4t^2$$

So the matrix representation of  $B$  relative to the basis  $S = \{1, t, t^2\}$  is

$$[B]_S = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \end{bmatrix}$$

its echelon form is

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 2 \end{bmatrix}$$

which is invertible. So  $B$  is an isomorphism.

**Question 9. (10 pts)**

A function  $f$  on the complex plane  $\mathbb{C}$  is defined by

$$f(z) = x^2 + x + 2ixy + iy - y^2,$$

where  $z = x + iy$ . Determine whether  $f$  is entire (that is, analytic on the whole complex plane  $\mathbb{C}$ ).

**Solution:**

$$u(x, y) = x^2 + x - y^2$$

$$v(x, y) = 2xy + y$$

We have

$$\frac{\partial u}{\partial x} = 2x + 1, \quad \frac{\partial u}{\partial y} = -2y$$

$$\frac{\partial v}{\partial x} = 2y, \quad \frac{\partial v}{\partial y} = 2x + 1$$

Clearly, all  $u, v, \frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial v}{\partial x}, \frac{\partial v}{\partial y}$  are continuous on  $\mathbb{C}$ . Moreover, the Cauchy-Riemann equations

$$\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} \quad \text{and} \quad \frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$$

are satisfied. Therefore,  $f$  is entire.

**Bonus Question 1. (5 pts)**

Consider the system of differential equations in Question 3 again:

$$\frac{d\mathbf{x}}{dt} = A\mathbf{x},$$

where  $A = \begin{bmatrix} 1 & -3 & 3 \\ 3 & -5 & 3 \\ 6 & -6 & 4 \end{bmatrix}$ . In Question 3, you have find the general solution  $\mathbf{x}(t)$  of the system. Fidin find a specific solution  $\mathbf{x}(t)$  such that

$$\mathbf{x}(0) = \begin{bmatrix} x_1(0) \\ x_2(0) \\ x_3(0) \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}$$

when  $t = 0$ . (Such a solution is called a solution of the above system with the given initial condition).

**Solution:** From the solution of Question 3, we have

$$\begin{bmatrix} x_1(0) \\ x_2(0) \\ x_3(0) \end{bmatrix} = \begin{bmatrix} c_1 + c_2 + c_3 \\ c_1 + c_3 \\ -c_2 + 2c_3 \end{bmatrix}.$$

Therefore, we need to solve for  $c_1, c_2$  and  $c_3$  of the following linear system

$$\begin{bmatrix} c_1 + c_2 + c_3 \\ c_1 + c_3 \\ -c_2 + 2c_3 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \\ 1 \end{bmatrix}$$

which has a unique solution  $c_1 = 2, c_2 = -3$  and  $c_3 = -1$ . So the solution satisfying the given initial condition is

$$\begin{bmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \end{bmatrix} = \begin{bmatrix} -e^{-2t} - e^{4t} \\ 2e^{-2t} - e^{4t} \\ 3e^{-2t} - 2e^{4t} \end{bmatrix}$$